

## Medium Payload Intelligent Robot

# FANUC Robot M-710iC



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## Features

The M-710iC is a medium payload robot with a wrist payload of 12 - 70kg. Eight models are available for a wide variety of applications.

### - FANUC Robot M-710iC/45M, /50, /70

Wide motion envelope and enough wrist load capacity to handle a large panel.

M-710iC/45M : Payload capacity 45kg

M-710iC/50 : Payload capacity 50kg

M-710iC/70 : Payload capacity 70kg

### - FANUC Robot M-710iC/50S

This model has a compact body that is suitable for narrow work environments. (Payload capacity 50kg)

### - FANUC Robot M-710iC/12L, /20L, /20M

Long reach and high motion performance make it suitable for many applications, such as handling, sealing and arc welding.

M-710iC/12L : Payload capacity 12kg (Hollow wrist)

M-710iC/20L : Payload capacity 20kg

M-710iC/20M : Payload capacity 20kg

### - FANUC Robot M-710iC/50H

This five-axes model is designed for the high speed transferring of parts. The ceiling mount option is ideal for compact handling systems. (Payload capacity 50kg)

- The full cover provides IP67-equivalent resistance to environmental conditions (dust and liquid). The M-710iC is reliable for various applications, such as load/unload for machined parts, de-burring and die cast loading.



## Application system



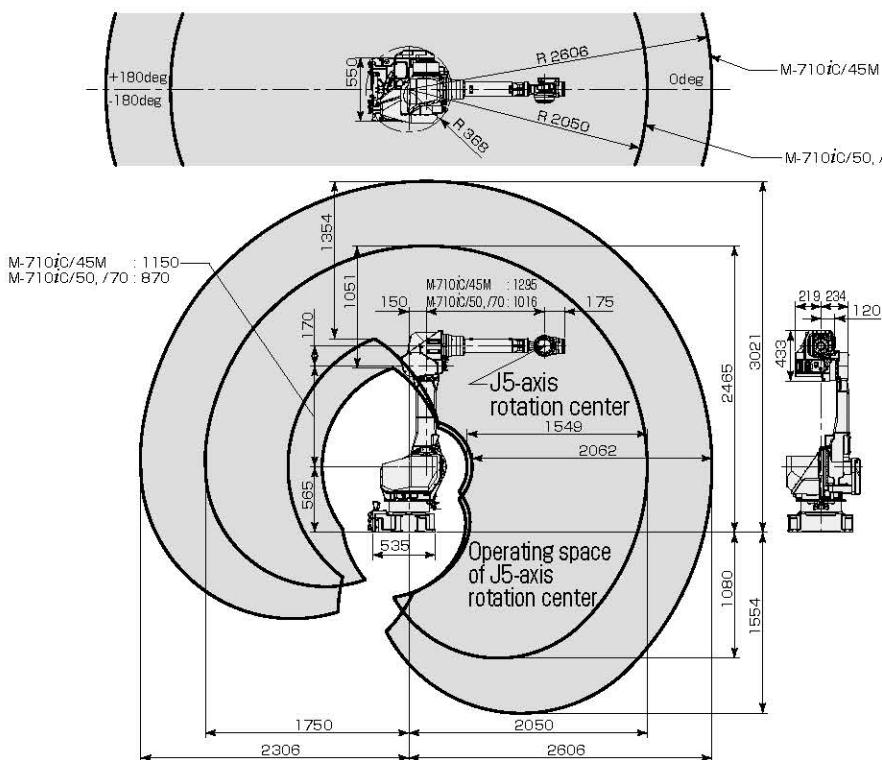
Bin picking of cylindrical parts



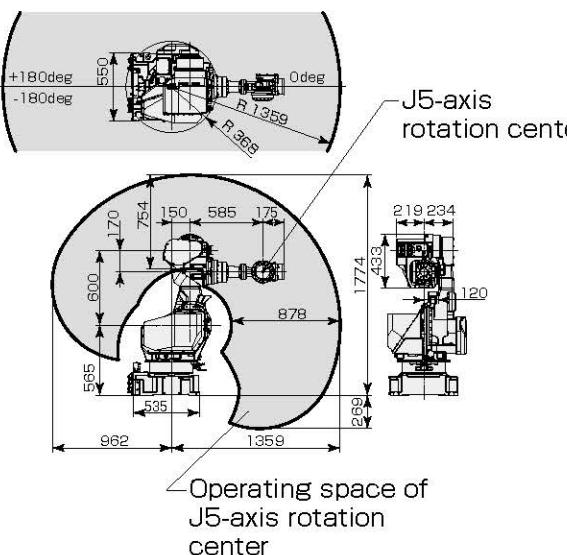
Car body sealing

# Operating space

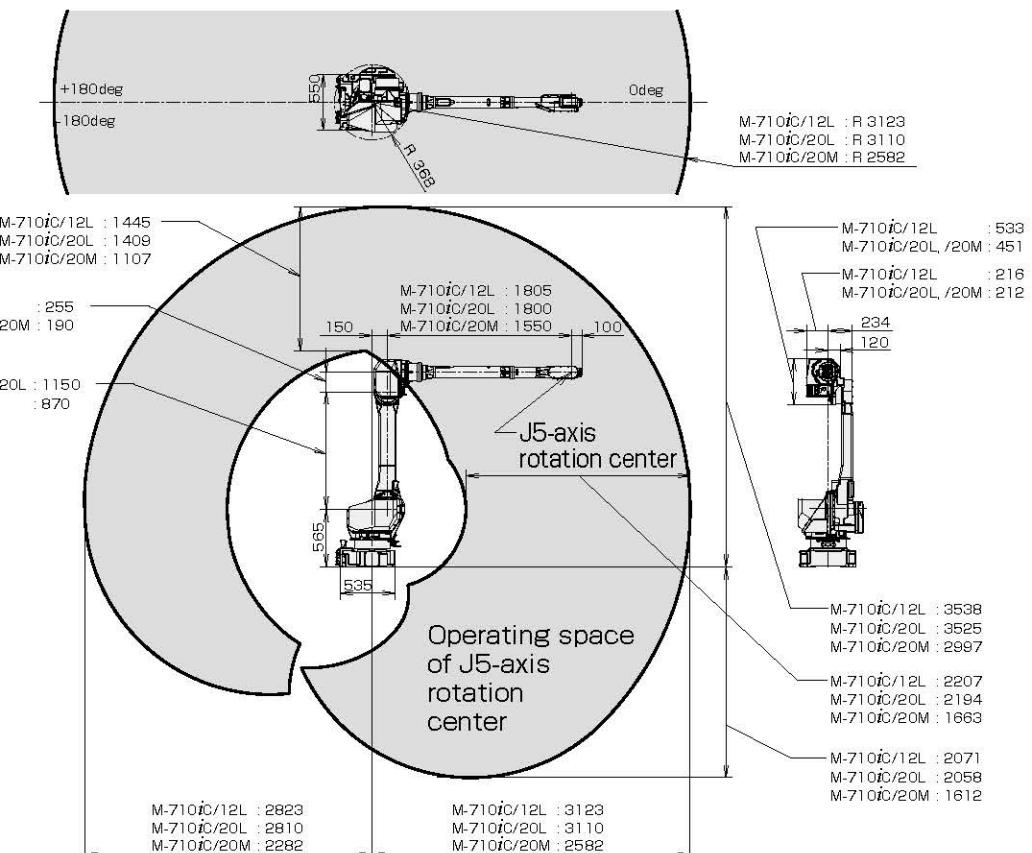
**M-710iC/45M,/50,/70**



**M-710iC/50S**



**M-710iC/12L,/20L,/20M**



## Specifications

Model	M-710iC/45M	M-710iC/50	M-710iC/70
Type	Articulated Type		
Controlled axes	6 axes (J1, J2, J3, J4, J5, J6)		
Reach	2606 mm	2050 mm	
Installation (Note 1)	Floor, Upside-down, Angle mount		
Motion range (Maximum speed) (Note 2)	J1 axis rotation 360° (180°/s) 6.28 rad (3.14 rad/s)	J2 axis rotation 225° (180°/s) 3.93 rad (3.14 rad/s)	J3 axis rotation 440° (180°/s) 7.68 rad (3.14 rad/s)
	J4 axis wrist rotation 800° (250°/s) 13.96 rad (4.36 rad/s)	J5 axis wrist rotation 250° (250°/s) 4.36 rad (4.36 rad/s)	J6 axis wrist rotation 800° (360°/s) 13.96 rad (6.28 rad/s)
	J2 axis rotation 225° (175°/s) 6.28 rad (3.05 rad/s)	J3 axis rotation 225° (120°/s) 3.93 rad (2.09 rad/s)	J4 axis rotation 360° (175°/s) 6.28 rad (3.05 rad/s)
	J5 axis rotation 169° (175°/s) 2.95 rad (3.05 rad/s)	J6 axis rotation 376° (175°/s) 6.56 rad (3.05 rad/s)	J1 axis rotation 169° (175°/s) 6.28 rad (3.05 rad/s)
	J6 axis rotation 720° (225°/s) 12.57 rad (4.36 rad/s)	J4 axis wrist rotation 720° (250°/s) 12.57 rad (4.36 rad/s)	J2 axis rotation 720° (225°/s) 12.57 rad (4.36 rad/s)
	J5 axis rotation 250° (225°/s) 4.36 rad (3.93 rad/s)	J5 axis wrist swing 250° (250°/s) 4.36 rad (4.36 rad/s)	J3 axis rotation 720° (225°/s) 12.57 rad (4.36 rad/s)
	J6 axis rotation 720° (355°/s) 12.57 rad (6.20 rad/s)	J6 axis wrist rotation 720° (355°/s) 12.57 rad (6.20 rad/s)	J4 axis rotation 720° (355°/s) 12.57 rad (6.20 rad/s)
Max. load capacity at wrist	45 kg	50 kg	70 kg
Max. Load capacity at J3 casing (Note 3)	15 kg		
Allowable load moment at wrist	J4 axis 206 N·m 206 N·m	J5 axis 21 kgf·m 294 N·m	J6 axis 13 kgf·m 147 N·m
	J5 axis 21 kgf·m	J6 axis 30 kgf·m	
Allowable load inertia at wrist	J4 axis 28 kg·m² 28 kg·m²	J5 axis 286 kgf·cm·s² 286 kgf·cm·s²	J6 axis 11 kg·m² 112 kgf·cm·s²
Drive method	Electric servo drive by AC servo motor		
Repeatability (Note 4)	± 0.06 mm	± 0.03 mm	± 0.04 mm
Mass (Note 5)	570 kg	560 kg	
Installation environment	Ambient temperature : 0 to 45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less		

Note 1) In case of the angle mounting, the J1 and J2 axis motion range are restricted.

Note 2) During short distance motions, the axis speed may not reach the maximum value stated.

Note 3) Max. load capacity at J3 casing is limited by payload at wrist.

Note 4) Compliant with ISO 9283.

Note 5) Without controller.

## Specifications

Model	M-710iC/50S	
Type	Articulated Type	
Controlled axes	6 axes (J1, J2, J3, J4, J5, J6)	
Reach	1359 mm	
Installation (Note 1)	Floor, Upside-down, Angle mount	
Motion range (Maximum speed) (Note 2)	J1 axis rotation 360° (180°/s) 6.28 rad (3.14 rad/s)	J2 axis rotation 225° (180°/s) 3.93 rad (3.14 rad/s)
	J3 axis rotation 440° (180°/s) 7.68 rad (3.14 rad/s)	J4 axis wrist rotation 800° (250°/s) 13.96 rad (4.36 rad/s)
	J4 axis rotation 360° (175°/s) 6.28 rad (3.05 rad/s)	J5 axis rotation 169° (175°/s) 2.95 rad (3.05 rad/s)
	J5 axis rotation 169° (175°/s) 2.95 rad (3.05 rad/s)	J6 axis rotation 376° (175°/s) 6.56 rad (3.05 rad/s)
	J6 axis rotation 720° (225°/s) 12.57 rad (4.36 rad/s)	J4 axis wrist rotation 720° (250°/s) 12.57 rad (4.36 rad/s)
	J5 axis rotation 720° (225°/s) 12.57 rad (4.36 rad/s)	J5 axis wrist swing 250° (250°/s) 4.36 rad (4.36 rad/s)
	J6 axis rotation 720° (355°/s) 12.57 rad (6.20 rad/s)	J6 axis wrist rotation 720° (355°/s) 12.57 rad (6.20 rad/s)
Max. load capacity at wrist	50 kg	
Max. Load capacity at J3 casing (Note 3)	15 kg	
Allowable load moment at wrist	J4 axis 206 N·m 206 N·m	J5 axis 21 kgf·m 294 N·m
	J6 axis 13 kgf·m 147 N·m	
Allowable load inertia at wrist	J4 axis 28 kg·m² 28 kg·m²	J5 axis 286 kgf·cm·s² 286 kgf·cm·s²
Drive method	Electric servo drive by AC servo motor	
Repeatability (Note 4)	± 0.04 mm	
Mass (Note 5)	545 kg	
Installation environment	Ambient temperature : 0 to 45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less	

Note 1) In case of the angle mounting, the J1 and J2 axis motion range are restricted.

Note 2) During short distance motions, the axis speed may not reach the maximum value stated.

Note 3) Max. load capacity at J3 casing is limited by payload at wrist.

Note 4) Compliant with ISO 9283.

Note 5) Without controller.

## Specifications

Model	M-710iC/12L	M-710iC/20L	M-710iC/20M
Type	Articulated Type		
Controlled axes	6 axes (J1, J2, J3, J4, J5, J6)	1310 mm	2582 mm
Reach	3123 mm		
Installation (Note 1)	Floor, Upside-down, Angle mount		
Motion range (Maximum speed) (Note 2)	J1 axis rotation 360° (180°/s) 6.28 rad (3.14 rad/s)	J2 axis rotation 225° (180°/s) 3.93 rad (3.14 rad/s)	J3 axis rotation 434° (180°/s) 7.57 rad (3.14 rad/s)
	J4 axis rotation 360° (175°/s) 6.28 rad (3.05 rad/s)	J5 axis rotation 225° (175°/s) 2.95 rad (3.05 rad/s)	J6 axis rotation 432° (180°/s) 7.54 rad (3.14 rad/s)
	J5 axis rotation 225° (175°/s) 2.95 rad (3.05 rad/s)	J6 axis rotation 400° (400°/s) 6.98 rad (6.98 rad/s)	J1 axis rotation 225° (175°/s) 6.28 rad (3.05 rad/s)
	J6 axis rotation 400° (400°/s) 6.98 rad (6.98 rad/s)	J5 axis rotation 380° (430°/s) 6.63 rad (7.50 rad/s)	J2 axis rotation 225° (175°/s) 2.95 rad (3.05 rad/s)
	J5 axis rotation 380° (430°/s) 6.63 rad (7.50 rad/s)	J6 axis rotation 280° (360°/s) 4.89 rad (6.28 rad/s)	J3 axis rotation 432° (180°/s) 7.54 rad (3.14 rad/s)
	J6 axis rotation 280° (360°/s) 12.57 rad (11.0 rad/s)	J7 axis rotation 900° (600°/s) 15.71 rad (10.47 rad/s)	J4 axis rotation 400° (350°/s) 6.98 rad (6.11 rad/s)
Max. load capacity at wrist	12 kg	20 kg	
Max. Load capacity at J3 casing (Note 3)	24 kg		
Allowable load moment at wrist	J4 axis 220 N·m 220 N·m	J5 axis 224 kgf·m 224 kgf·m	J6 axis 9.8 N·m 1.0 kgf·m
	J6 axis 2.0 kgf·m		J1 axis 39.2 N·m 4.0 kgf·m
Allowable load inertia at wrist	J4 axis 0.65 kg·m² 0.66 kgf·cm·s²	J5 axis 0.65 kg·m² 0.66 kgf·cm·s²	J6 axis 0.88 kg·m² 0.90 kgf·cm·s²
Drive method	Electric servo drive by AC servo motor		
Repeatability (Note 4)	± 0.09 mm	± 0.06 mm	± 0.06 mm
Mass (Note 5)	540 kg	530 kg	
Installation environment	Ambient temperature : 0 to 45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less		

Note 1) In case of the angle mounting, the J1 and J2 axis motion range are restricted.

Note 2) During short distance motions, the axis speed may not reach the maximum value stated.

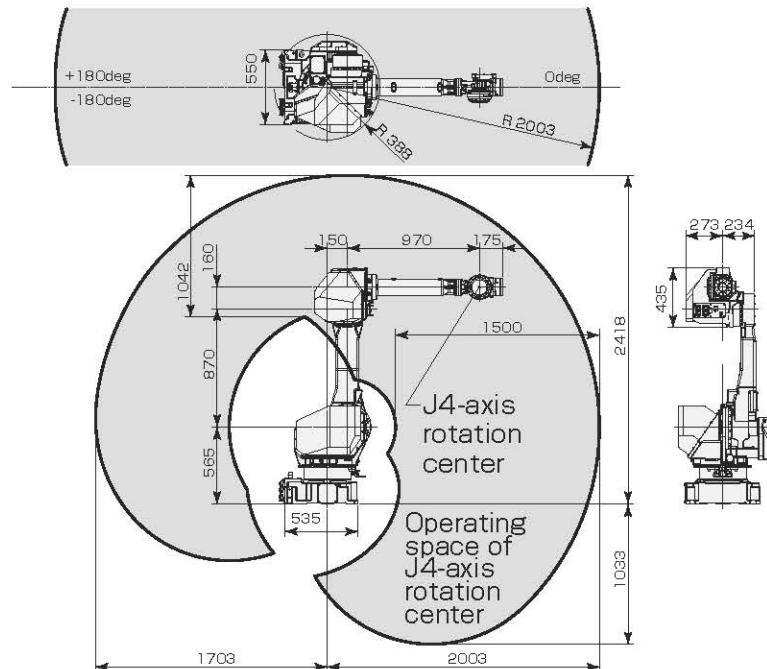
Note 3) Max. load capacity at J3 casing is limited by payload at wrist.

Note 4) Compliant with ISO 9283.

Note 5) Without controller.

# Operating space

## M-710iC/50H



## Specifications

Model		M-710iC/50H	
Type		Articulated Type	
Controlled axes		5 axes (J1, J2, J3, J4, J5)	
Reach		2003 mm	
Installation		Floor, Upside-down	
Motion range (Maximum speed) (Note 1)	J1 axis rotation	360° (175°/s) 6.28 rad (3.05 rad/s)	
	J2 axis rotation	225° (175°/s) 3.93 rad (3.05 rad/s)	
	J3 axis rotation	440° (175°/s) 7.68 rad (3.05 rad/s)	
	J4 axis wrist swing	234° (175°/s) 4.08 rad (3.05 rad/s)	
	J5 axis wrist rotation	720° (720°/s) 12.57 rad (12.57 rad/s)	
Max. load capacity at wrist		50 kg	
Max. load capacity at J3 casing (Note 2)		15 kg	
Allowable load moment at wrist	J4 axis	150 N·m 15.3 kgf·m	
	J5 axis	68 N·m 6.9 kgf·m	
Allowable load inertia at wrist	J4 axis	6.3 kg·m <sup>2</sup> 64.3 kgf·cm·s <sup>2</sup>	
	J5 axis	2.5 kg·m <sup>2</sup> 25.5 kgf·cm·s <sup>2</sup>	
Drive method		Electric servo drive by AC servo motor	
Repeatability		± 0.15 mm	
Mass (Note 3)		540 kg	
Installation environment		Ambient temperature : 0 to 45°C	
		Ambient humidity : Normally 75%RH or less (No dew nor frost allowed)	
		Short term 95%RH or less (within one month)	
		Vibration acceleration : 4.9m/s <sup>2</sup> (0.5G) or less	

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Max. load capacity at J3 casing is limited by payload at wrist.

Note 3) Without controller.

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