

FANUC

Fast, slim and accurate handling robot



The compact solution for maximum performance

- new slim and lightweight design to increase productivity
- compact arm and wrist to minimise interference against peripheral equipment and fixtures
- ideal solution for compact production line installations
- smooth finishing to reduce collection of dust and dirt
- easy installation and seamlessly integrated routing of user cable handling dressout eliminate interference from peripherals and work cell equipment
- intelligent maintenance schedule with Zero Down Time software by smartly predicting mechanical and process equipment status





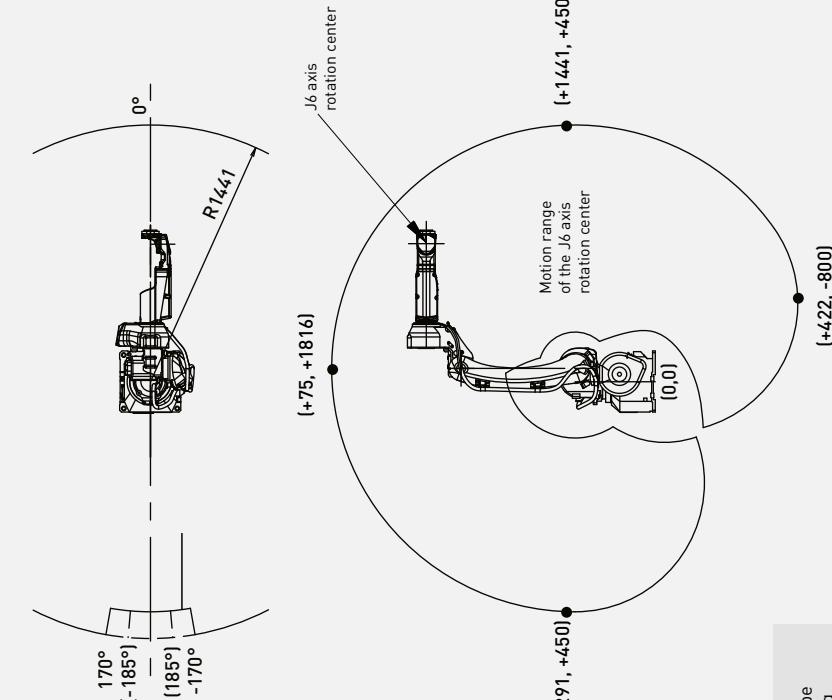
M-10iD/12 (Hollow wrist)

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motioncontrolrobotics.com

Controlled axes	Repeatability [mm]	Mechanical weight [kg]	Motion range [°]						Maximum speed [°/s]			J5 Moment/Inertia [Nm/kgm ²]	J6 Moment/Inertia [Nm/kgm ²]		
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6	
6	± 0.02*	145	340 (370)	235	455	380	360	900	260	240	260	450	720	26.0/0.90	26.0/0.30

Working range



Motion range may be restricted according to the mounting angle!

Robot

- Robot footprint [mm]
- Mounting position Floor
- Mounting position Upside down
- Mounting position Angle

Controller

- Open air cabinet
- Mate cabinet
- A-cabinet
- B-cabinet
- iPendant Touch

Electrical connections

- Voltage 50/60Hz 3phase [V]
- Voltage 50/60Hz 1 phase [V]
- Average power consumption [kW]

Integrated services

- Integrated signals on upper arm In/Out
- Integrated air supply

Environment

- Acoustic noise level [dB]
- Ambient temperature [°C]

Protection

- Body standard/optional
- Wrist & J3 arm standard/optional

IP64 /IP55

IP67

Max. reach:
1441 mm

Max. load capacity
at wrist: 12 kg

*Based on IS09283

• standard o on request - not available () with hardware and/or software option