

# M-710iC/70T (Top mount)



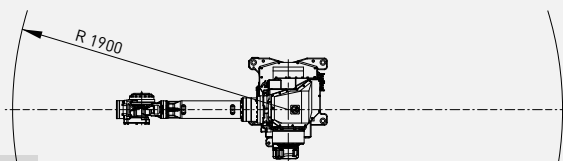
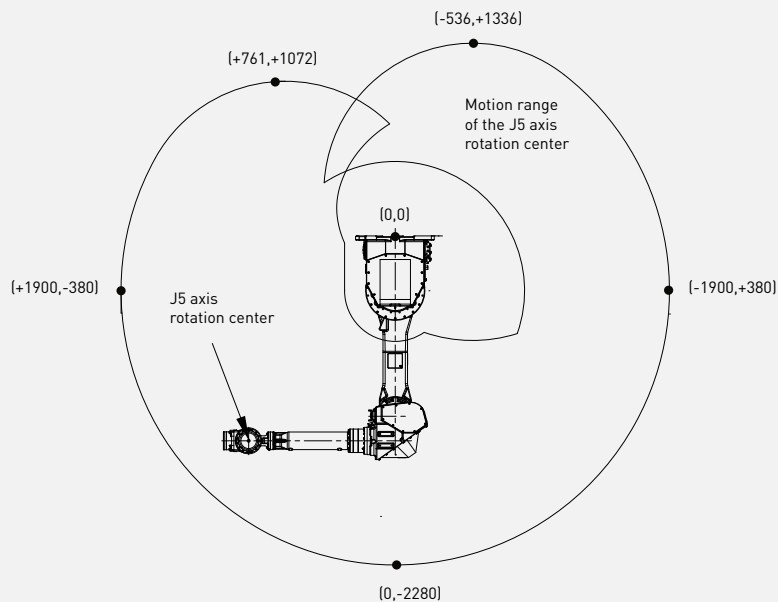
Max. load capacity at wrist: **70 kg**



Max. reach: **1900 mm**

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						J4 Moment/Inertia (Nm/kgm <sup>2</sup> )	J5 Moment/Inertia (Nm/kgm <sup>2</sup> )	J6 Moment/Inertia (Nm/kgm <sup>2</sup> )
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6			
6	± 0.07	410	*1	261	491	720	250	720	*1	120	120	225	225	225	294/28	294/28	147/11

## Working range



Motion range may be restricted according to the mounting angle!

## Robot

	M-710iC/70T
Robot footprint [mm]	535 X 550
Mounting position Floor	●
Mounting position Upside down	●
Mounting position Angle	●

## Controller

	R-30iB Plus
Open air cabinet	-
Mate cabinet	○
A-cabinet	●
B-cabinet	○
iPendant Touch	●

## Electrical connections

Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	2.5

## Integrated services

Integrated signals on upper arm In/Out	8/8
Integrated air supply	1

## Environment

Acoustic noise level [dB]	71.3
Ambient temperature [° C]	0-45

## Protection

Body standard/optional	IP54/IP67
Wrist & J3 arm standard/optional	IP67

\*1) depending on rail specification

● standard ○ on request - not available ( ) with hardware and/or software option