

CRX-25iA

FANUC



Max. load capacity
at wrist: 25 kg



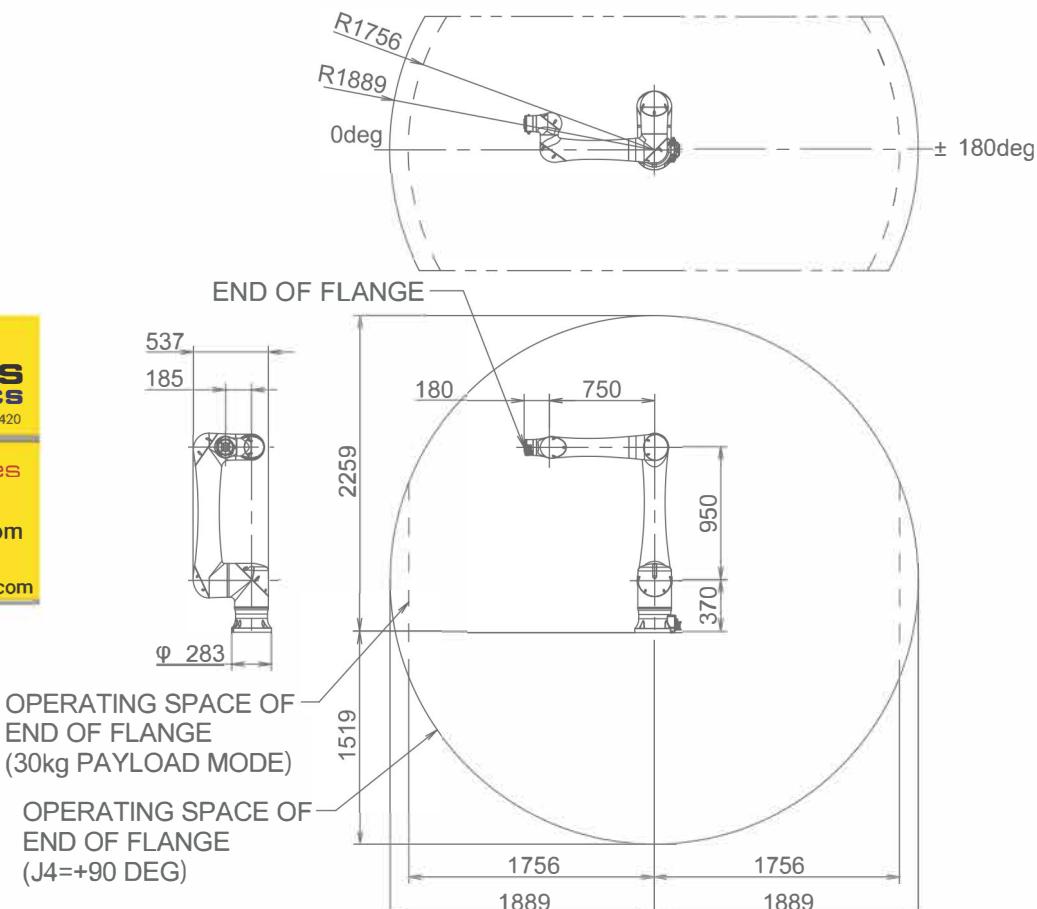
Max. reach
(end of flange):
1889 mm

| Robot | | | Series | Version | Type | Max. load capacity at wrist [kg] | ***Reach [mm] | Controlled axes | **Repeatability [mm] | Mechanical weight [kg] | Motion range [°] | | | | | | *Maximum speed [°/s] | | ***Allowable Wrist Load | | | Protection |
|-------|----|----|---------|-------------|------|----------------------------------|--------------------------|-------------------|----------------------|------------------------|--------------------------|-----|-----|------|------|----------|----------------------|-----------|-------------------------|------|------|------------|
| J1 | J2 | J3 | J4 | J5 | J6 | Collaborative Mode [mm/sec] | High Speed Mode [mm/sec] | J4 Moment/Inertia | J5 Moment/Inertia | J6 Moment/Inertia | Input power source [VAC] | | | | | | | | | | | |
| CRX | iA | 25 | 25 [30] | 1889 [1756] | 6 | ± 0.05 | 135 | 360 | 360 | 540 | 380 | 360 | 450 | 1000 | 2000 | 1000/4.7 | 74.0/4.00 | 32.0/2.00 | 100-120 200-240 | IP67 | IP67 | |

● standard O on request - not available () Operating space is restricted when 30kg payload mode is selected * During short distance, it may not reach the maximum value stated. Please set motion speed according to risk assessment of system. ** Based on ISO9283 ***Nm/Kg.m² ****At the end of flange

CRX-25iA

Standard model



CRX-25iA