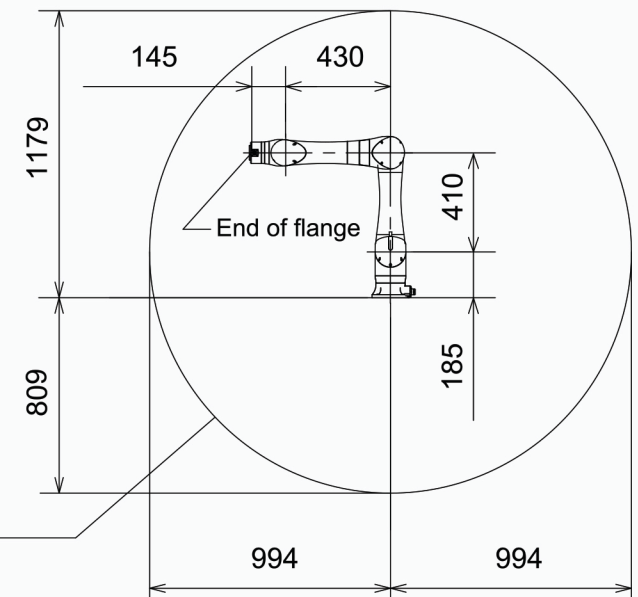
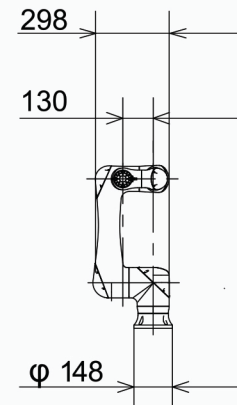
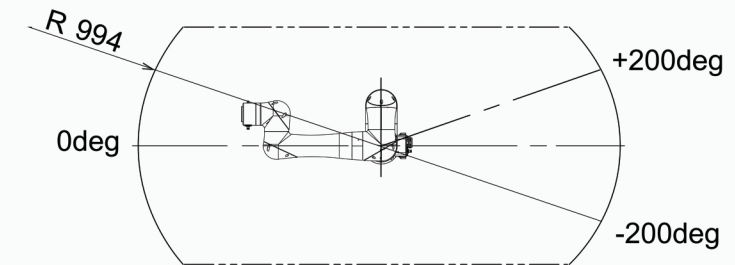


Series	Robot		Max.load capacity at wrist (kg)	****Reach (mm)	Controlled axes	**Repeatability (mm)	Mechanical weight (kg)	Motion range [°]						*Maximum speed [°/s]		***Allowable Wrist Load			Input power source (VAC)	Protection	
	Version	Type						J1	J2	J3	J4	J5	J6	Collaborative Mode [mm/sec]	High Speed Mode [mm/sec]	J4 Moment/ Inertia	J5 Moment/ Inertia	J6 Moment/ Inertia		Body standard	Wrist & J3 arm
CRX	iA	5	5	994	6	± 0.03	25	400	360	635	380	360	450	1000	2000	19/ 0.77	15.4/ 0.5	6.7/ 0.1	100-120 200-240	IP67	IP67

● standard ○ on request - not available * During short distance, it may not reach the maximum value stated. Please set motion speed according to risk assessment of system. ** Based on ISO9283 ***Nm/Kg.m² ****At the end of flange

CRX-5*iA*

Standard model



Operating Space
of End of Flange
(J4 +90 deg.)