

CRX-3iA



Max. load capacity
at wrist: 3kg



Max. reach
(end of flange):
692 mm

FANUC

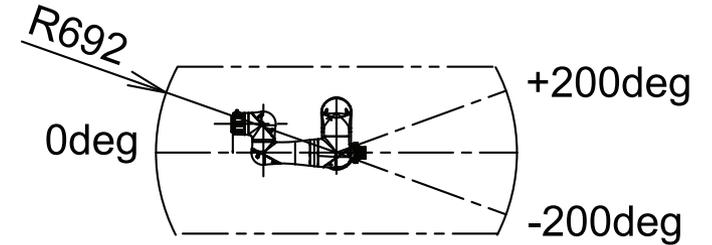
| Robot | | | Max. load capacity at wrist (kg) | ****Reach (mm) | Controlled axes | **Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | *Maximum speed (°/s) | | ***Allowable Wrist Load | | | Protection | | |
|--------|---------|------|----------------------------------|----------------|-----------------|----------------------|------------------------|------------------|-----|-----|-----|-----|-----|-----------------------------|--------------------------|-------------------------|--------------------|--------------------|--------------------------|---------------|----------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | Collaborative Mode [mm/sec] | High Speed Mode [mm/sec] | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Input power source (VAC) | Body standard | Wrist & J3 arm |
| CRX | iA | 3 | 3 | 692 | 6 | ±0.02 | 11 | 400 | 360 | 592 | 380 | 360 | 450 | 1200 | 2500 | 8.5/ 0.32 | 6.5/ 0.24 | 4/ 0.08 | | | |

● standard ○ on request - not available * During short distance, it may not reach the maximum value stated. Please set motion speed according to risk assessment of system. ** Based on ISO9283 ***Nm/Kg.m² ****At the end of flange

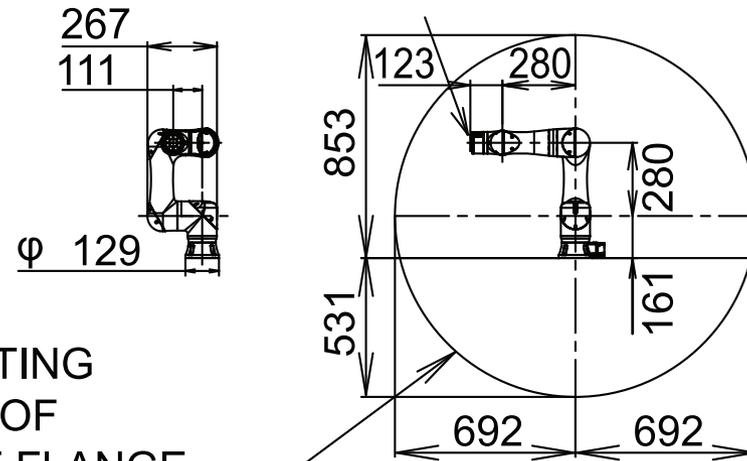
CRX-3iA Standard model



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END OF FLANGE



OPERATING SPACE OF END OF FLANGE (J4=+90 DEG)