FANUC Robot CR-41A, 71A, 71A/L





Features

The FANUC compact collaborative robot line-up is a small, human arm sized six-axis 4kg-7kg payload robot with short, standard and long arm variants available. The collaborative robot can be wall or invert mounted to save floor space.

Three models are available for various reach/payload needs:

- FANUC Robot CR-4iA short arm variant with 4kg payload
- FANUC Robot CR-7iA standard arm with 7kg payload
- FANUC Robot CR-7iA/L long arm variant with 7kg payload

Collaborative Operation

 The CR line-up of robots can operate in cooperation with or alongside humans in a shared workspace without safety fences or sensors.

Safety Function

- The collaborative robots stop safely in the event of contact with a human operator.
- The collaborative robots can be pushed out of the way at anytime with minimal force.
- The CR line-up is certified to meet the requirements of ISO 10218-1 for collaborative robots.

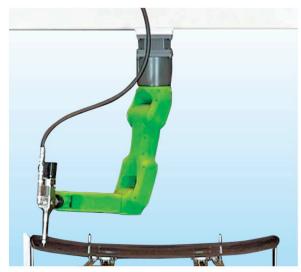
Intelligence and High Reliability

- Robot is immediately ready for use with on board solenoid operated air valves as standard equipment.
- Latest intelligent functions such as force sensing and iRVision (Integrated vision) are available.
- The FANUC collaborative robots are designed with the same high reliability as all FANUC robots.

Application Examples

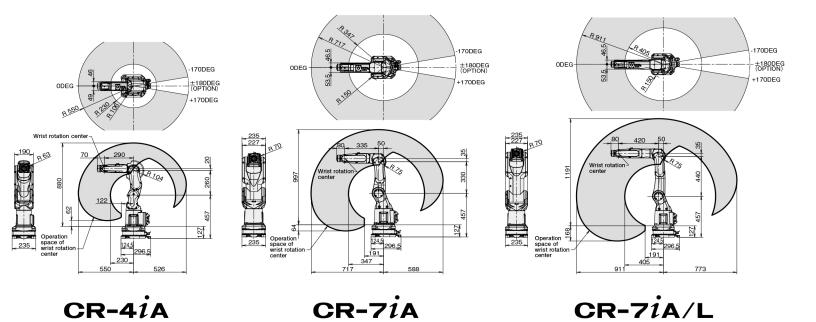


Circuit Board Assembly



Apply Adhesive to Windshield (Up-side Down)

Operating space



Specifications

	CR-4 i A		G	CR-7 <i>i</i> A		CR-7 <i>î</i> A/L	
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)					
Reach		50 mm	71	17 mm	91	1 mm	
Installation (Note 1)		Floor, Upside-down, Wall					
J1 axis	340°	5.93 rad	340°	5.93 rad	340°	5.93 rad	
J2 axis	150°	2.61 rad	166°	2.89 rad	166°	2.89 rad	
J3 axis	354°	6.17 rad	373°	6.51 rad	383°	6.68 rad	
J4 axis	380°	6.63 rad	380°	6.63 rad	380°	6.63 rad	
J5 axis	200°	3.49 rad	240°	4.18 rad	240°	4.18 rad	
J6 axis	720°	12.57 rad	720°	12.57 rad	720°	12.57 rad	
z. load capacity at wrist (Note 2) 4 kg		4 kg	7 kg 7 kg			7 kg	
Maximum speed (Note 3)		500 mm/s (Max 1000 mm/s Note 4)					
Allowable load J4 axis		8.86 N·m		16.6 N⋅m		16.6 N⋅m	
J5 axis	8.86 N⋅m		16.	16.6 N⋅m		16.6 N·m	
moment at wrist J6 axis		4.90 N⋅m		9.4 N·m		9.4 N·m	
J4 axis	0.20 kg·m²		0.4	0.47 kg·m²		0.47 kg·m²	
Allowable load inertia at wrist J5 axis	0.20 kg⋅m²		0.4	0.47 kg·m²		0.47 kg⋅m²	
J6 axis		0.067 kg·m ²		0.15 kg·m²		0.15 kg⋅m²	
	±0.02 mm		±0.	±0.02 mm		±0.03 mm	
	48 kg		É	53 kg		55 kg	
nment	Ambient temperature : 0 to 45°C Ambient humidity : Normally 75 %RH or less (No dew nor frost allowed) Short term Max.95 %RH or less (within one month)						
	J1 axis J2 axis J3 axis J4 axis J5 axis J6 axis at wrist (Note 2) Note 3) J4 axis J5 axis J6 axis J6 axis J6 axis J6 axis	J1 axis 340° J2 axis 150° J3 axis 354° J4 axis 380° J5 axis 200° J6 axis 720° at wrist (Note 2) 300° Note 3) 300° J4 axis 8.3 J5 axis 8.3 J6 axis 4.3 J5 axis 0.2 J6 axis 0.2 J6 axis 0.2 Ambient ter Ambient ter Ambient human	J1 axis 340° 5.93 rad J2 axis 150° 2.61 rad J3 axis 354° 6.17 rad J4 axis 380° 6.63 rad J5 axis 200° 3.49 rad J6 axis 720° 12.57 rad at wrist (Note 2) 4 kg Note 3) 8.86 N·m J5 axis 8.86 N·m J6 axis 4.90 N·m J4 axis 0.20 kg·m² J5 axis 0.20 kg·m² J6 axis 0.067 kg·m² ±0.02 mm 48 kg Ambient temperature Ambient humidity	J1 axis 340° 5.93 rad 340° J2 axis 150° 2.61 rad 166° J3 axis 354° 6.17 rad 373° J4 axis 380° 6.63 rad 380° J5 axis 200° 3.49 rad 240° J6 axis 720° 12.57 rad 720° at wrist (Note 2) 4 kg Note 3) 500 mm/s (Max J4 axis 8.86 N·m 16 J5 axis 8.86 N·m 16 J6 axis 4.90 N·m 9. J4 axis 0.20 kg·m² 0.4 J5 axis 0.20 kg·m² 0.4 J6 axis 0.067 kg·m² 0.1 J7 axis 0.1 0.1 J7 axis 0.1 0.1 J7 axis 0.20 kg·m² 0.4	J1 axis 340° 5.93 rad 340° 5.93 rad J2 axis 150° 2.61 rad 166° 2.89 rad J3 axis 354° 6.17 rad 373° 6.51 rad J4 axis 380° 6.63 rad 380° 6.63 rad J5 axis 200° 3.49 rad 240° 4.18 rad J6 axis 720° 12.57 rad 720° 12.57 rad at wrist (Note 2) 4 kg 7 kg Note 3) 500 mm/s (Max 1000 mm/s Note J4 axis 8.86 N·m 16.6 N·m J5 axis 8.86 N·m 16.6 N·m J6 axis 4.90 N·m 9.4 N·m J4 axis 0.20 kg·m² 0.47 kg·m² J5 axis 0.20 kg·m² 0.47 kg·m² J6 axis 0.067 kg·m² 0.15 kg·m² J6 axis 0.067 kg·m² 0.15 kg·m² J6 axis 0.007 kg·m² 0.15 kg·m² J6 axis 0.007 kg·m² 0.15 kg·m² J6 axis 0.007 kg·m² 0.15 kg·m² J7 kg 0.15 kg·m² 0.15 kg·m² J7 kg 0.15 kg·m	J1 axis 340° 5.93 rad 340° 5.93 rad 340° J2 axis 150° 2.61 rad 166° 2.89 rad 166° J3 axis 354° 6.17 rad 373° 6.51 rad 383° J4 axis 380° 6.63 rad 380° 6.63 rad 380° J5 axis 200° 3.49 rad 240° 4.18 rad 240° J6 axis 720° 12.57 rad 720° 12.57 rad 720° at wrist (Note 2) 4 kg 7 kg 7 7 Note 3) 500 mm/s (Max 1000 mm/s Note 4) 500 mm/s Note 4) 16.6 N⋅m 16.6 N⋅m <t< td=""></t<>	

Note 1) In case of the wall mount, the operation space will be restricted according with the payload.

Note 2) A total weight including the equipment and connection cables and its swing must not exceed this value when you install the equipment.

Note 3) During short distance motions, the speed may not reach the maximum value stated.

Note 4) If the area is monitored by a safety sensor (located separately).

Note 5) Without controller.



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